

What Periodic Trajectories Exist
for a Particle Subjected to a
Central Force $F = -r^{-\frac{1}{2}}$?

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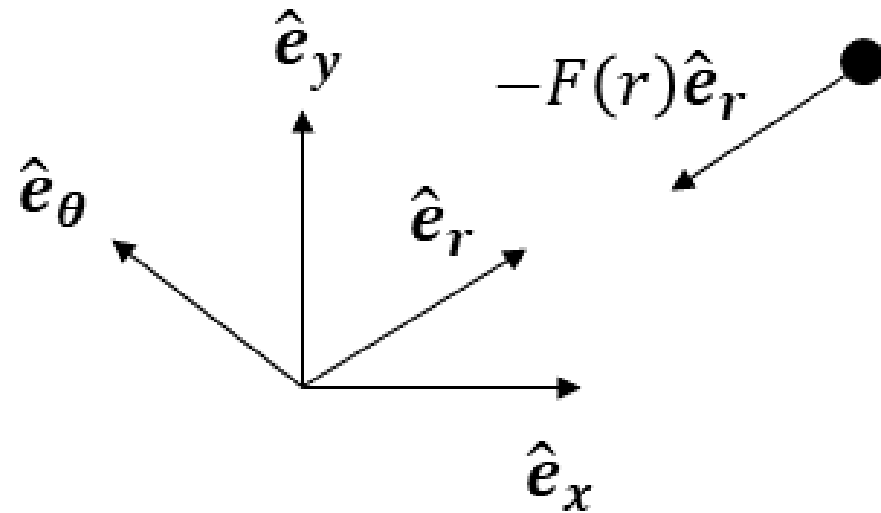
Background

- A central force is one that can be written as $\mathbf{F} = F(r)\hat{\mathbf{e}}_r$.
- For the central force $F(r) = -r^{-\frac{1}{2}}$, the equations of motion in Cartesian are:

$$\ddot{x} = F \frac{x}{r}$$

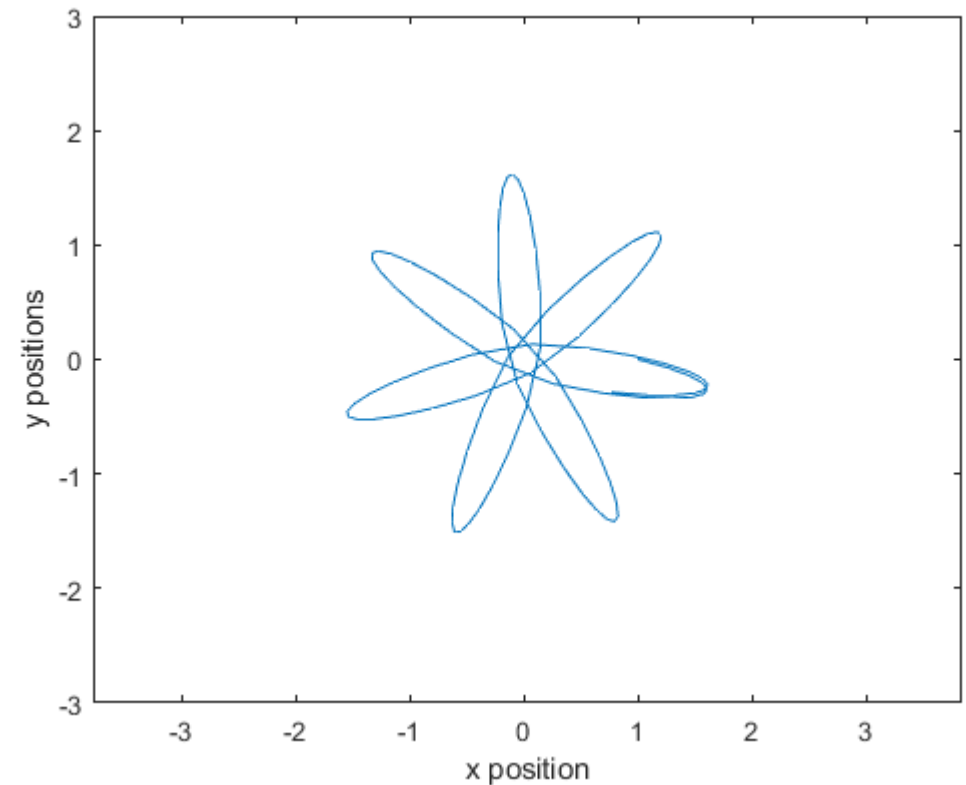
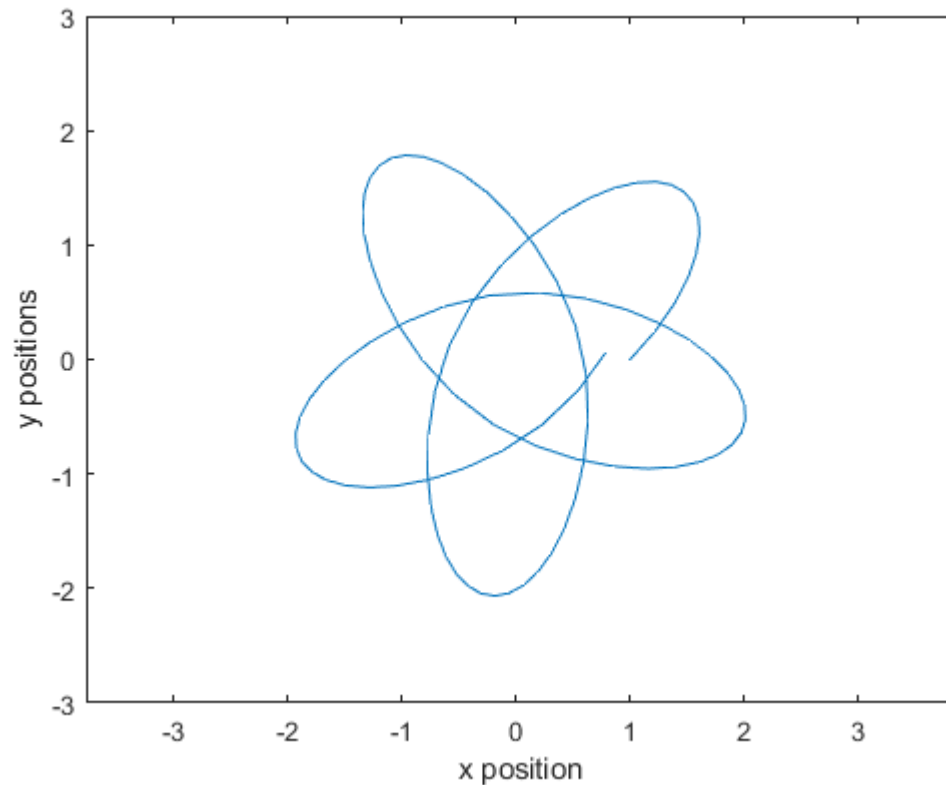
$$\ddot{y} = F \frac{y}{r}$$

$$r = \sqrt{x^2 + y^2}$$



Motivation

There appears to exist periodic trajectories that are neither linear nor circular when subjected to the central force $F(r) = r^{-\frac{1}{2}}$.

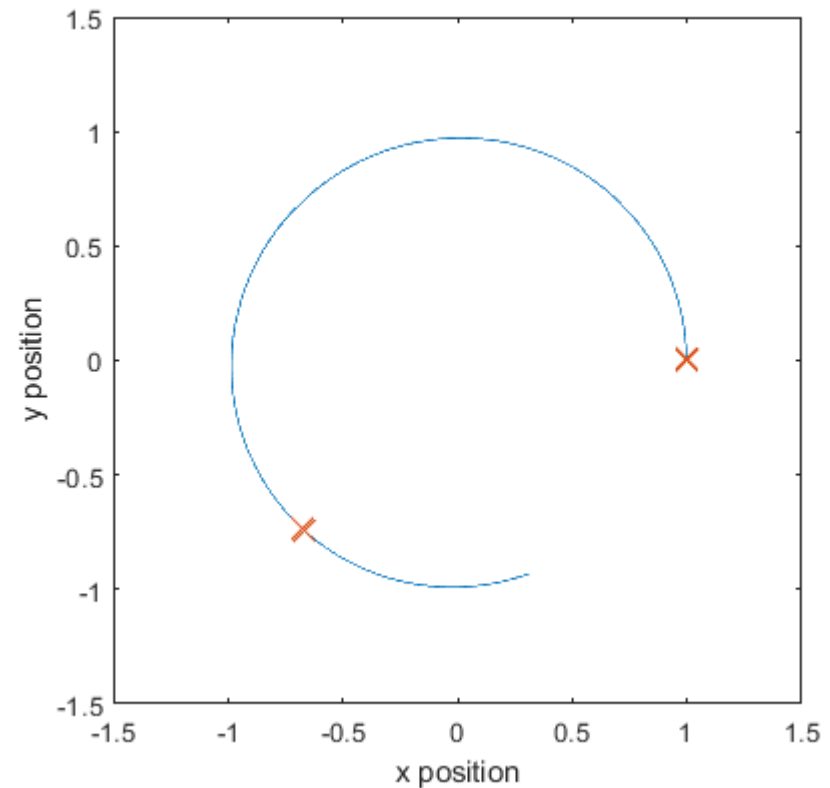
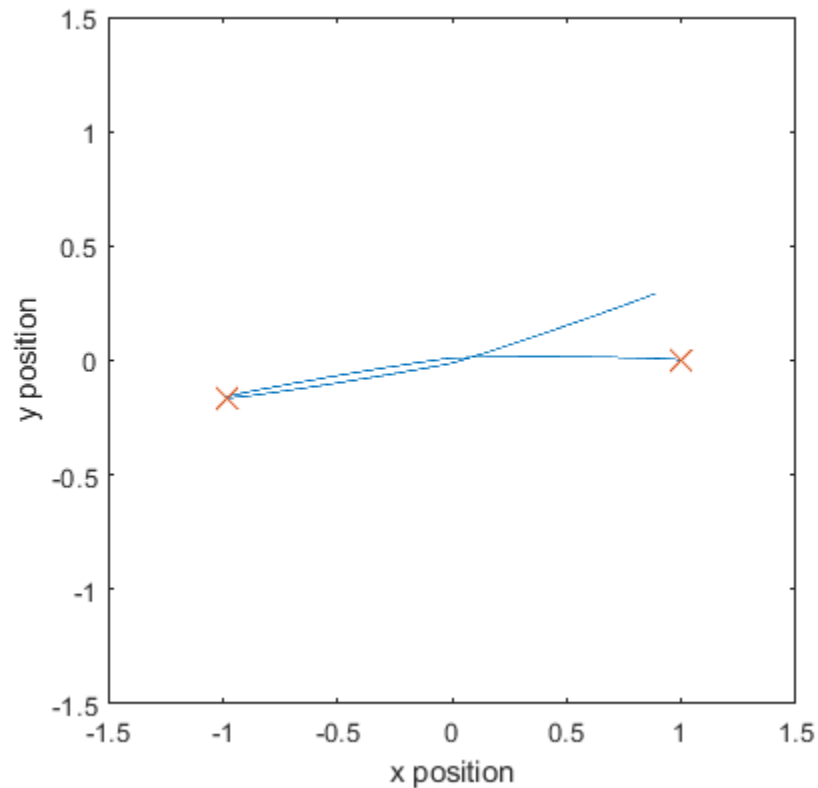


Finding Possible Solutions

- All trajectories lie between a line and a circle.
 - Linear trajectory has no velocity or acceleration in the \hat{e}_θ direction.
 - Circular trajectory has no acceleration in the \hat{e}_r direction.
- How fast does a particle need to be traveling to move in a circle?
 - Written in polar, the acceleration after setting $\dot{r} = \ddot{r} = 0$ is
$$\mathbf{a} = -r\dot{\theta}^2\hat{e}_r + r\ddot{\theta}\hat{e}_\theta = \frac{v^2}{r}\hat{e}_r + r\ddot{\theta}\hat{e}_\theta$$
 - Use LMB and dot in \hat{e}_r : $v = r^{\frac{1}{4}}$
- Start particle with $[x \ y \ \dot{x} \ \dot{y}] = [1 \ 0 \ 0 \ v]$, $v \in [0, 1]$.
- Look at extremes of the velocity, specifically when v is close to 0 and when v is close to 1.

Boundaries of Possible Trajectories

- The location of the next lobe is bounded by $\sim(180^\circ, 227.7^\circ)$ away from the first lobe.
- This corresponds with travelling $\sim(0.5, 0.6325)$ of a circle.



No Lobed Solutions

- No solution containing 3 lobes, 4 lobes, 6 lobes, 10 lobes and 14 lobes.
- Check up to 3000, check in the same way to see if it's between the two bounds.
- Appears that the only ones without solutions are the ones listed above.

Solutions

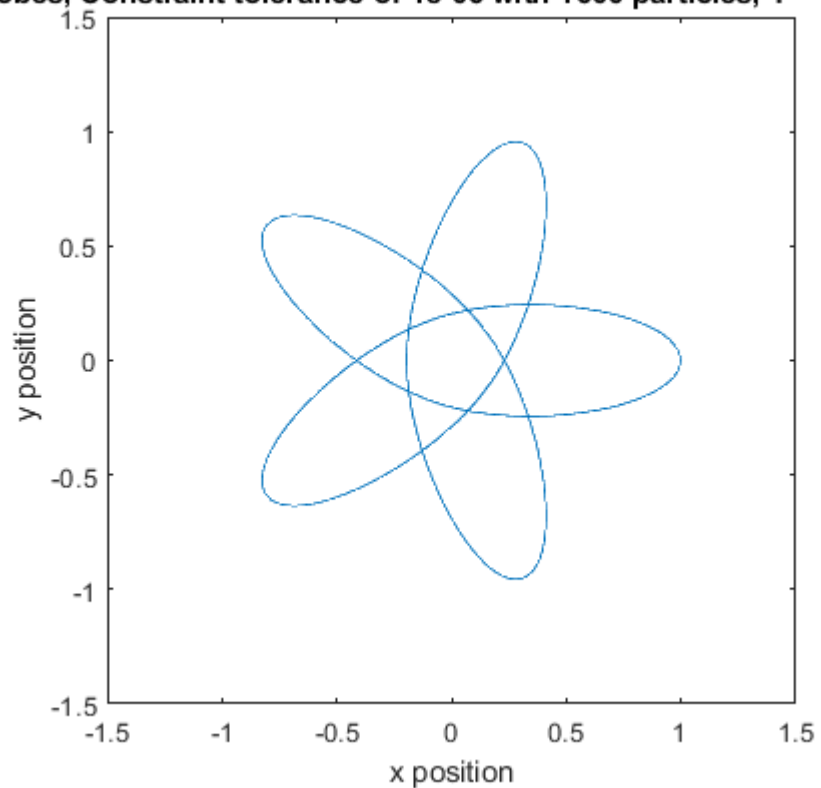
- Trajectory optimization was used to find periodic trajectories that are neither linear nor circular.
- The following solutions were primarily achieved using single shooting.
- The time it took the NLP to find a solution with the desired tolerance depended on:
 - Initial guess
 - Constraints
 - Number of parameters it could control

Helping the Trajectory Optimizer Converge

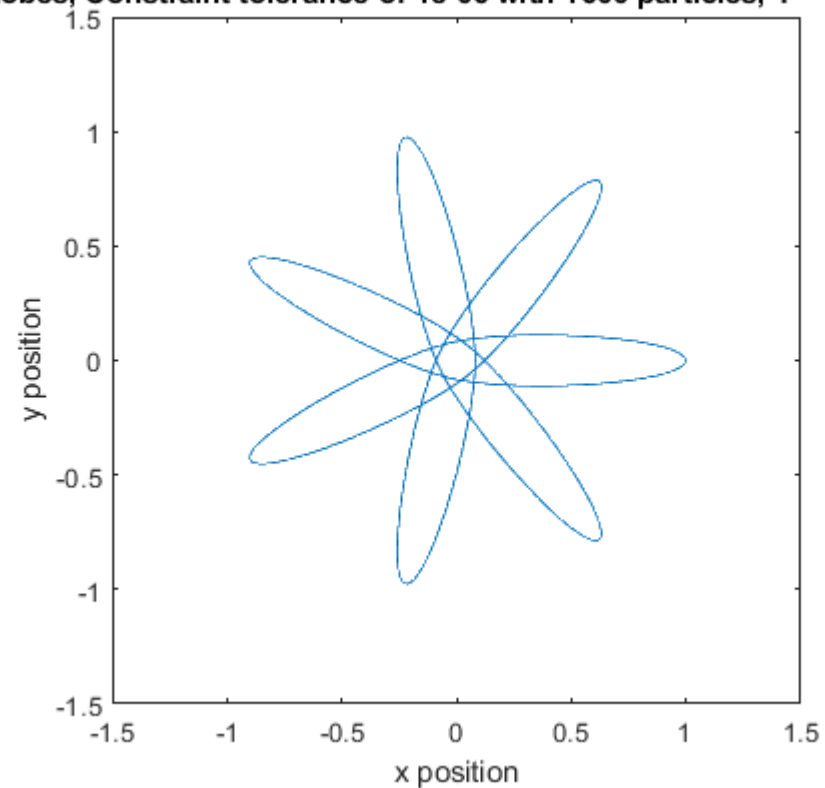
- Iterate. Start with a less tight tolerance, then step up the tolerance. Also start with a smaller number of points, and increase the number of points
- Impose constraints as tight as possible; double check that they are reasonable for the desired goal.
- Put at minimum a lower bound on time to prevent solutions that barely move.

Central Force $F = -r^{-\frac{1}{2}}$

5 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 14.1586 s

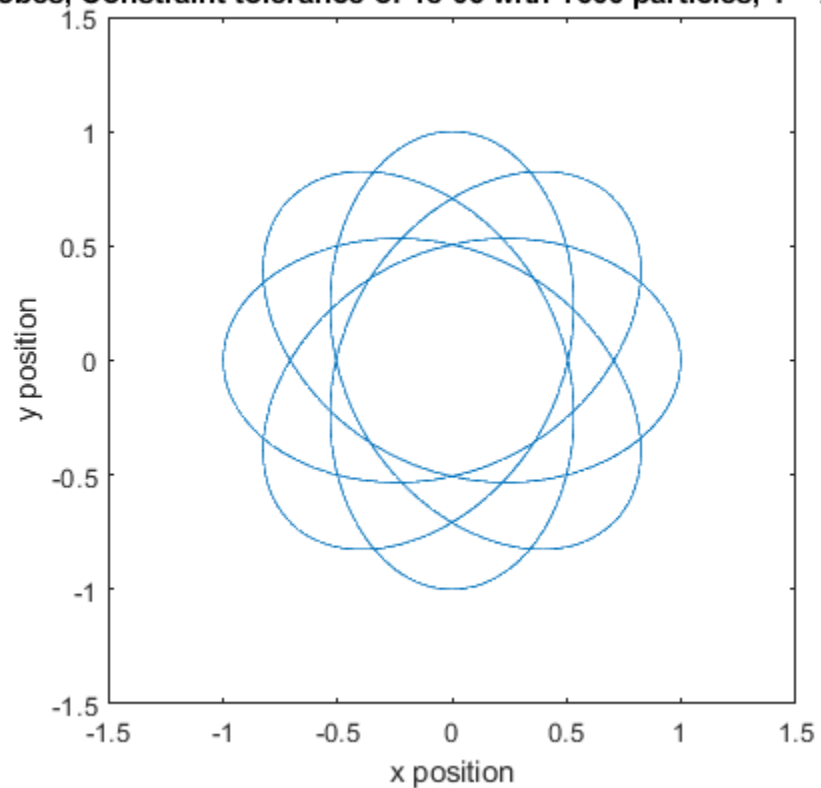


7 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 18.9964 s

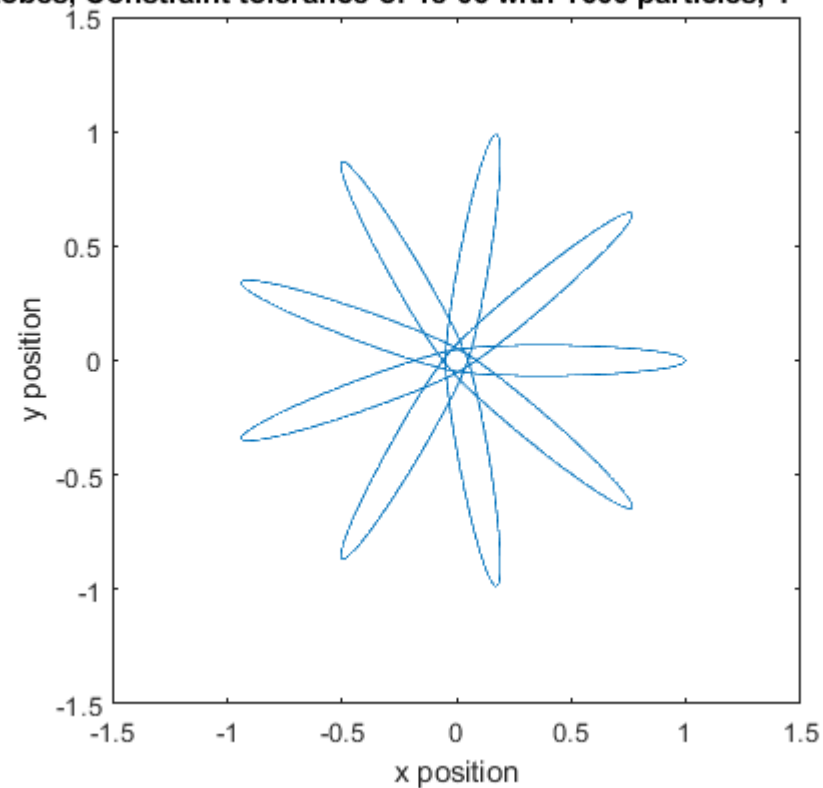


Central Force $F = -r^{-\frac{1}{2}}$

8 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 25.7385 s

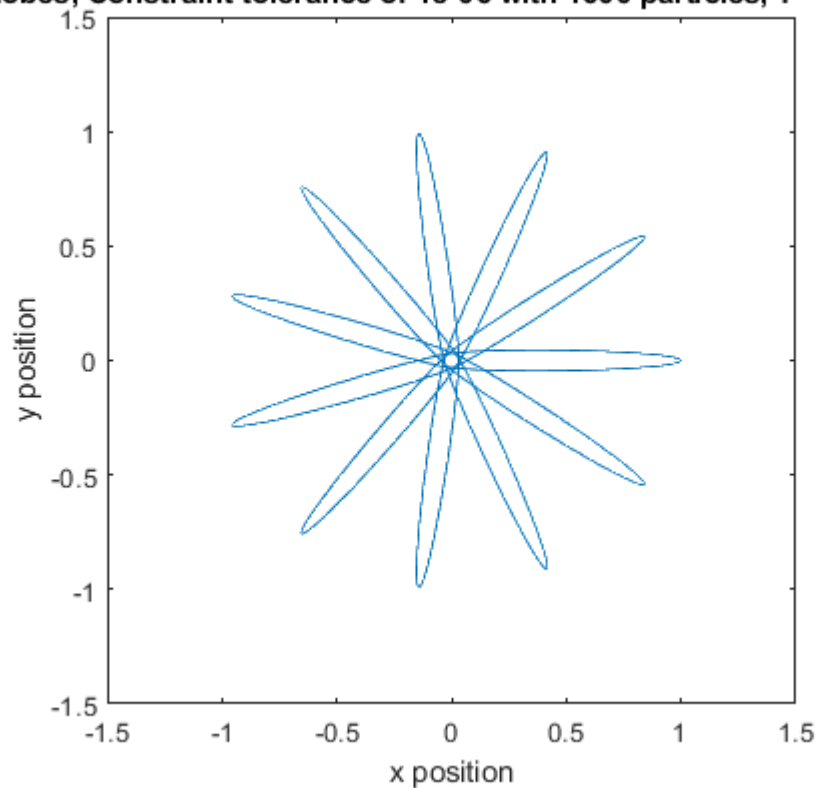


9 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 24.1761 s

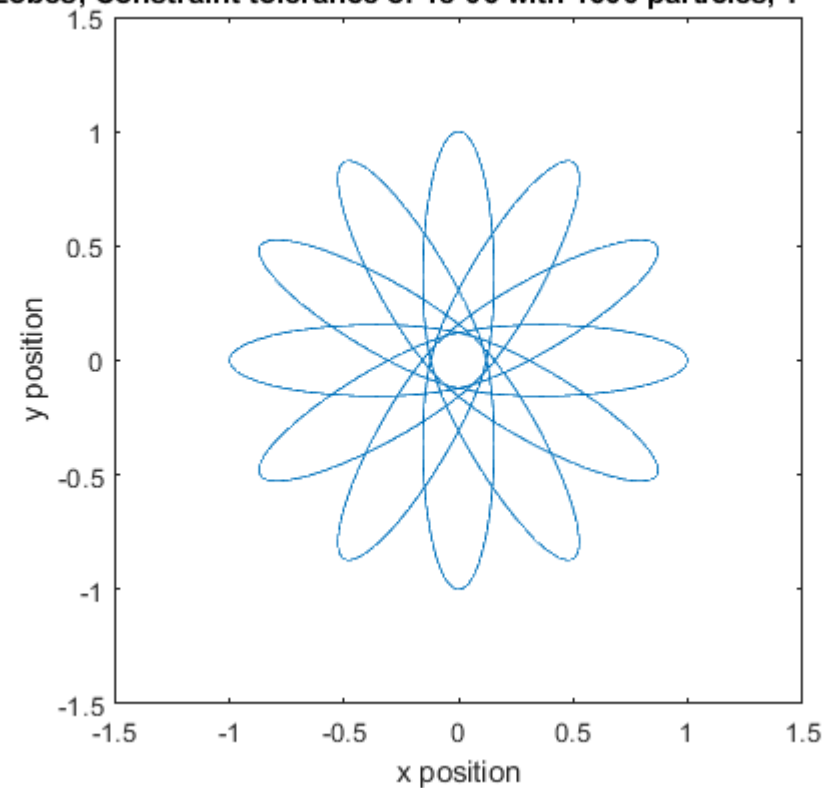


Central Force $F = -r^{-\frac{1}{2}}$

11 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 29.4467 s

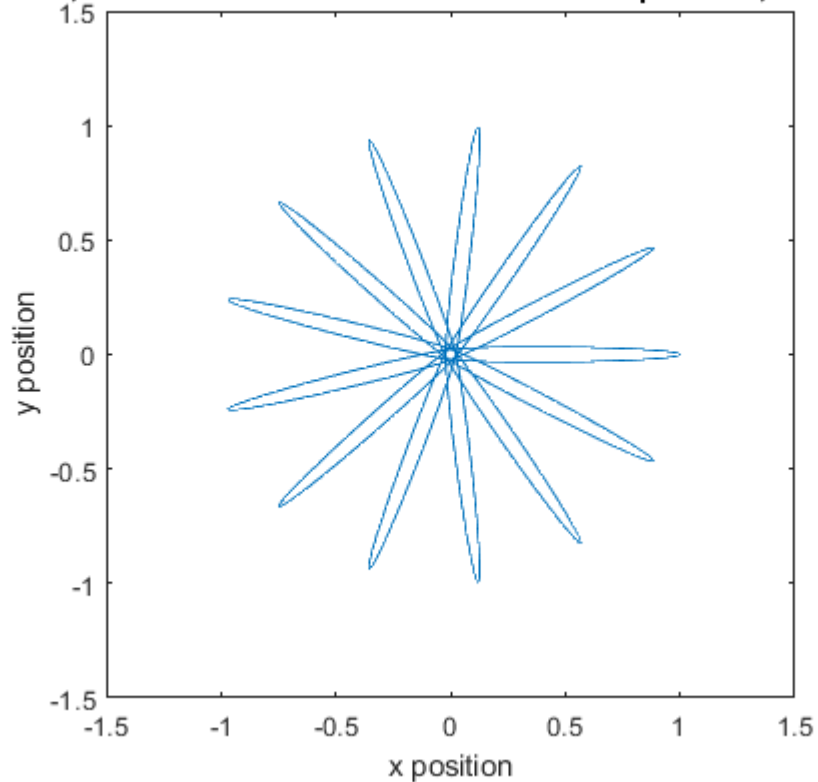


12 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 32.9478 s

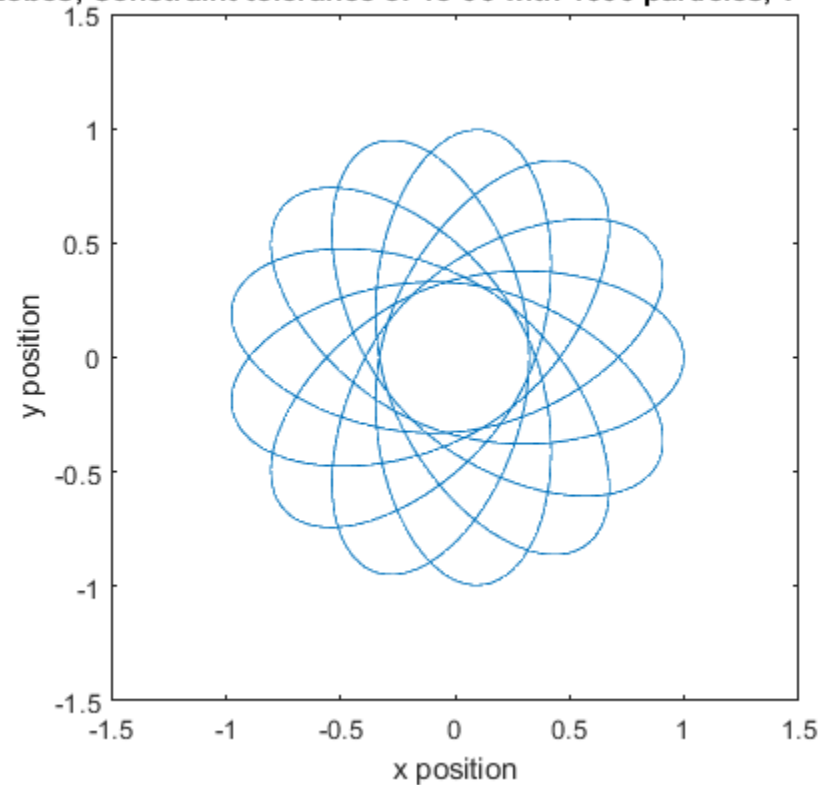


Central Force $F = -r^{-\frac{1}{2}}$

13 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 34.7463 s

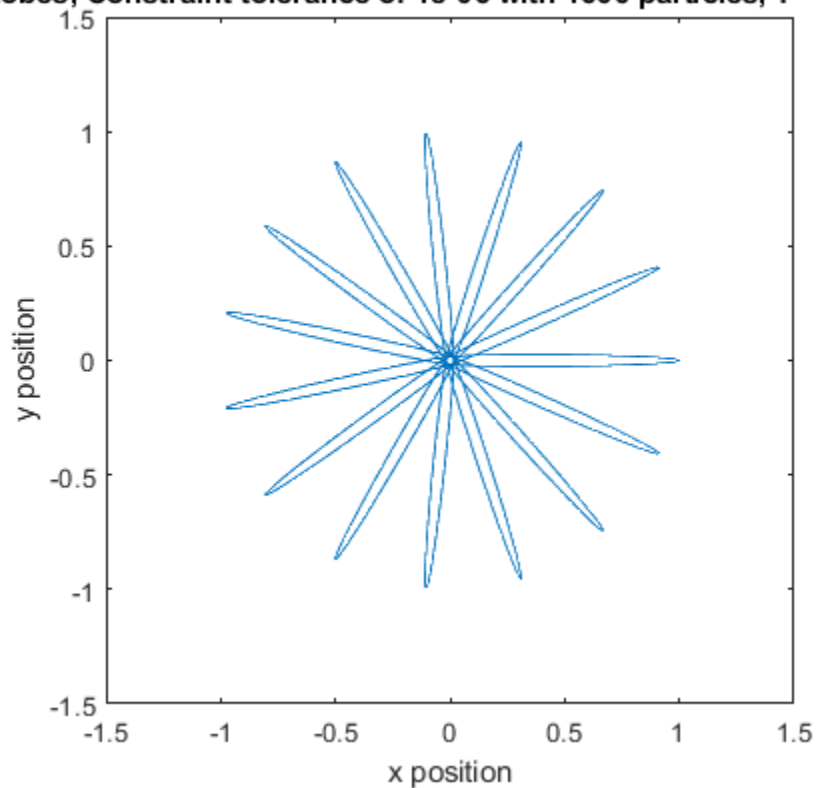


13 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 38.9035 s

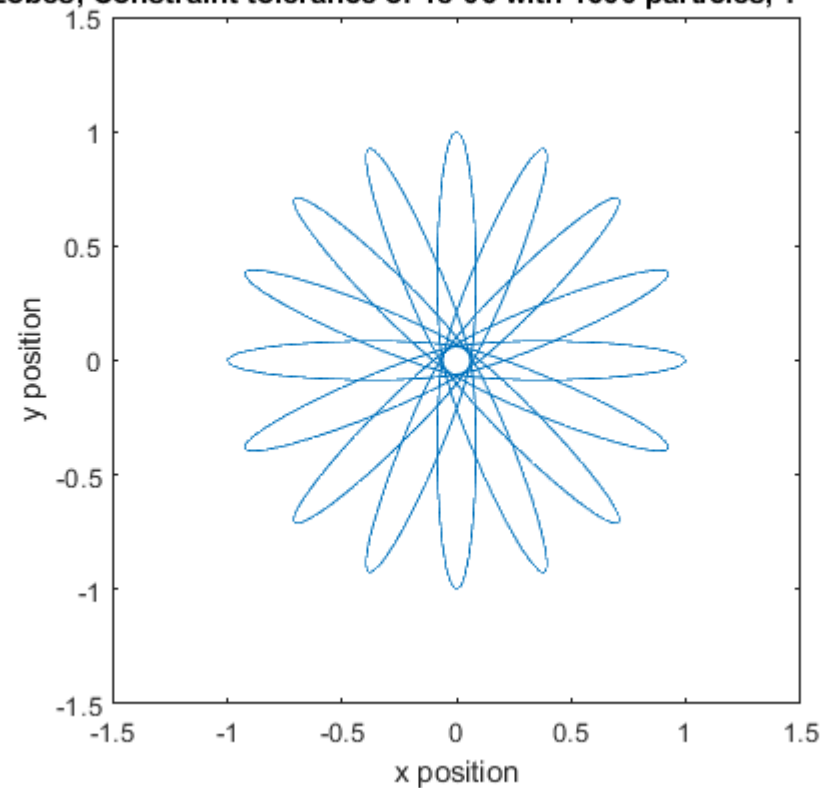


Central Force $F = -r^{-\frac{1}{2}}$

15 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 40.0592 s

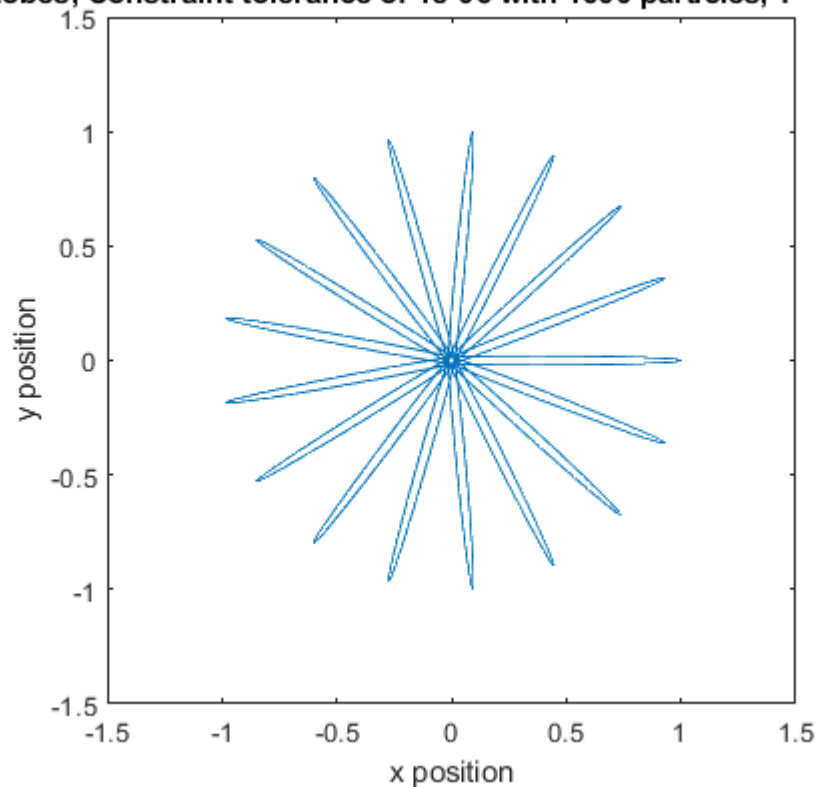


16 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 43.1279 s

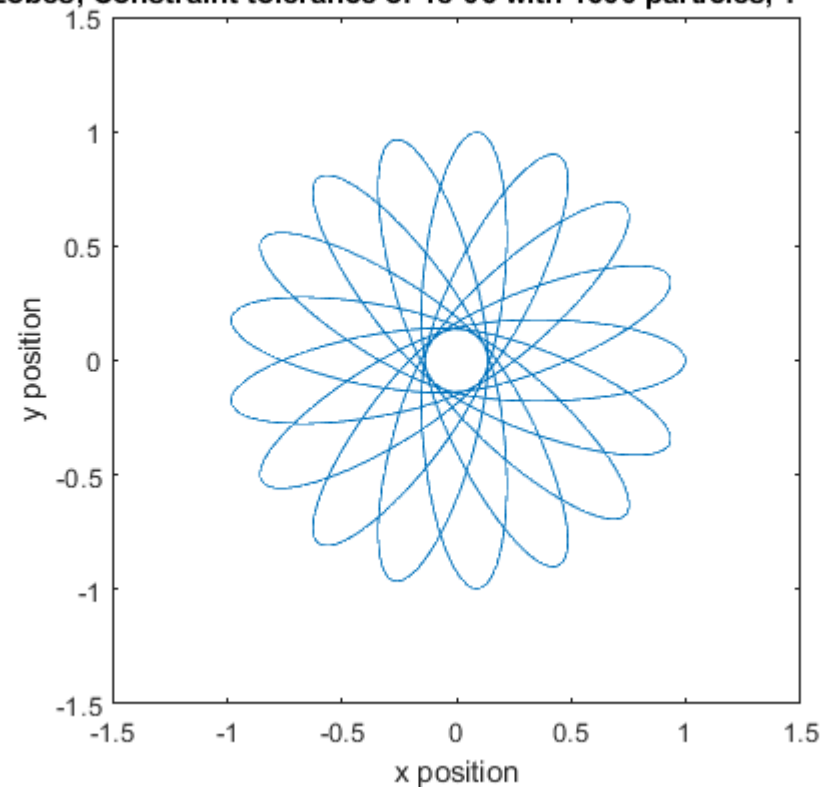


Central Force $F = -r^{-\frac{1}{2}}$

17 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 45.3792 s

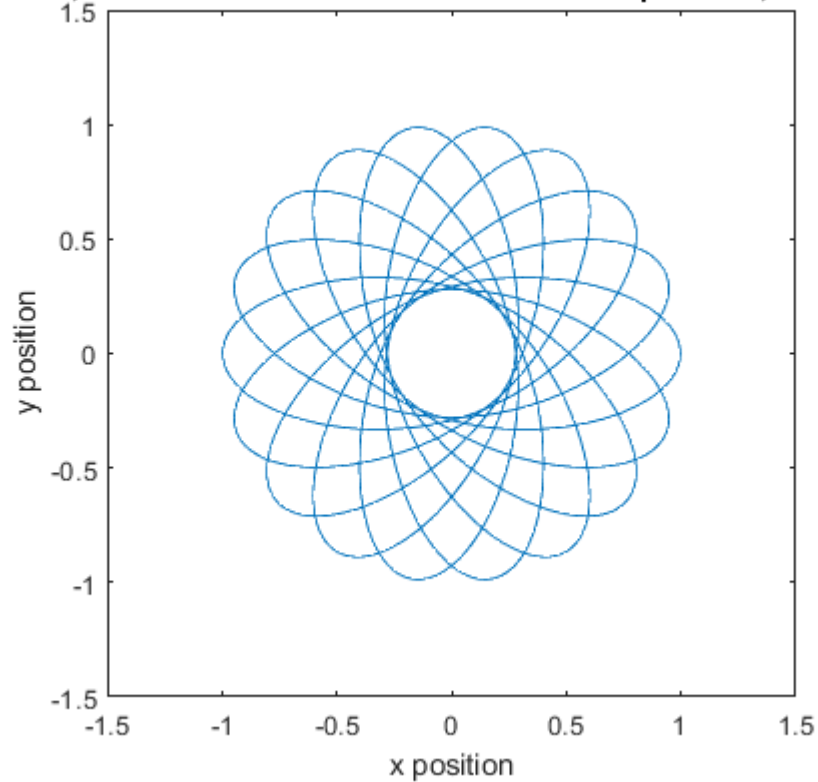


17 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 47.0012 s

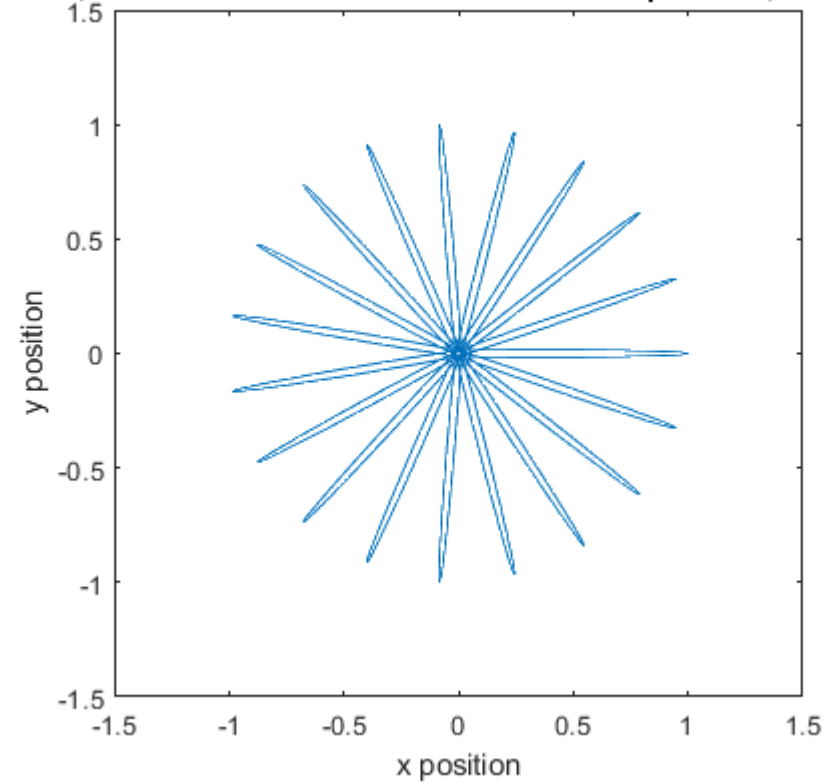


Central Force $F = -r^{-\frac{1}{2}}$

18 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 52.8003 s

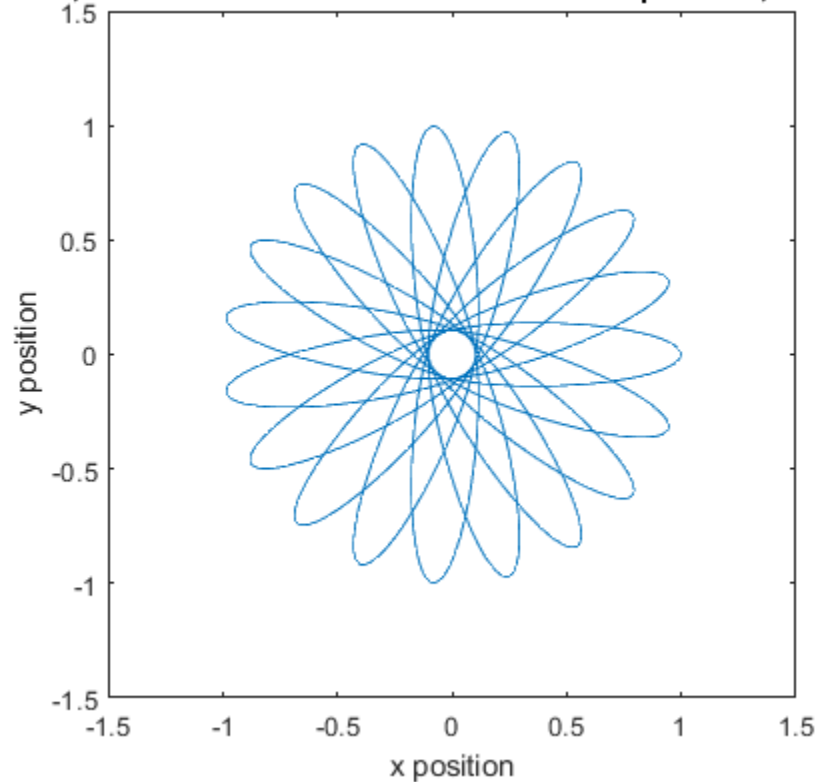


19 Lobes, Constraint tolerance of 1e-05 with 1600 particles, T = 50.7033 s

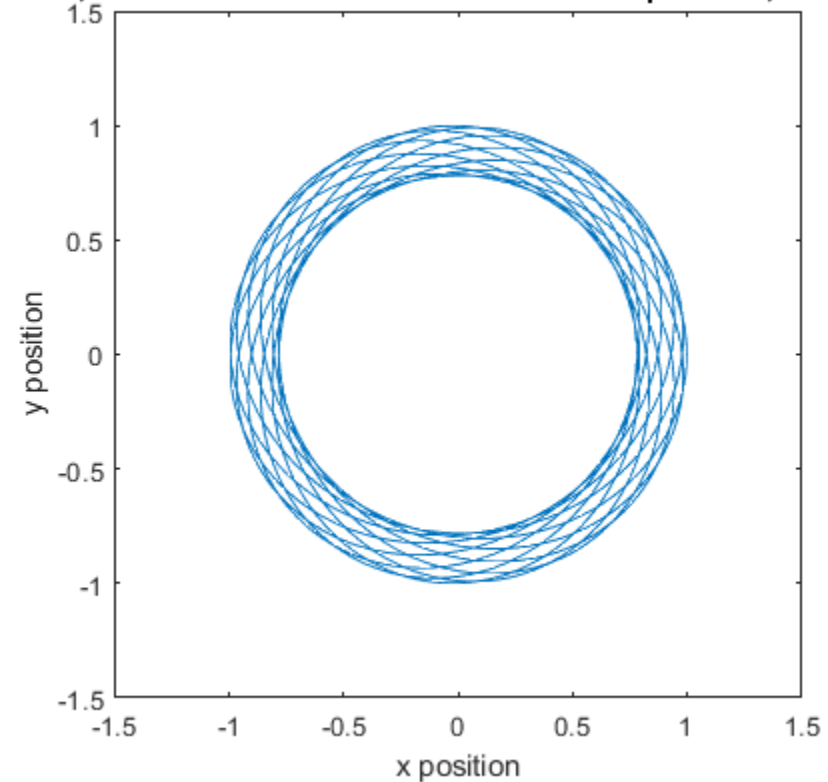


Central Force $F = -r^{-\frac{1}{2}}$

19 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 51.9294 s

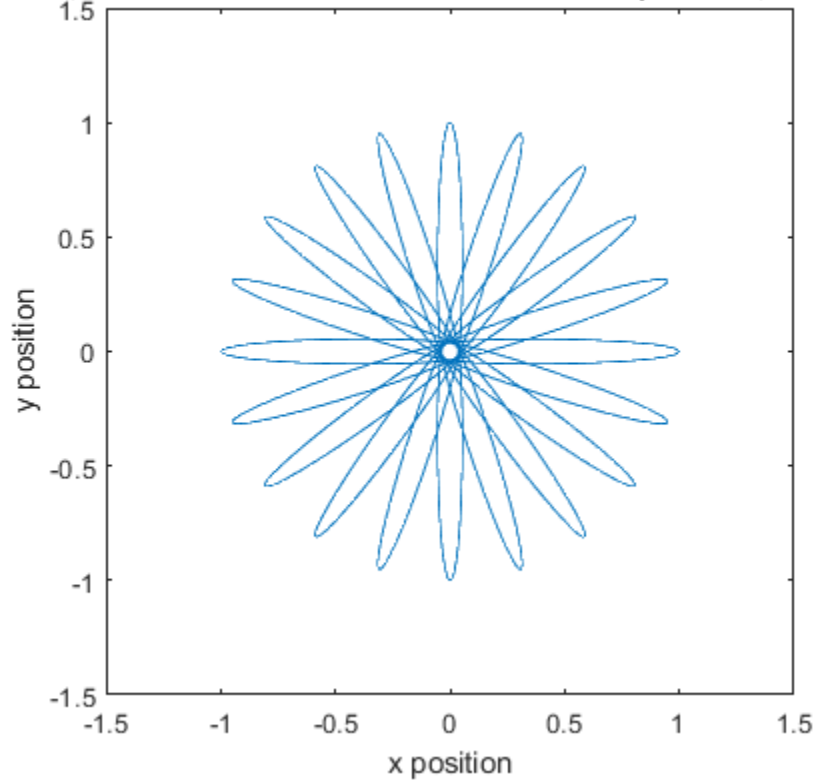


19 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 69.3873 s

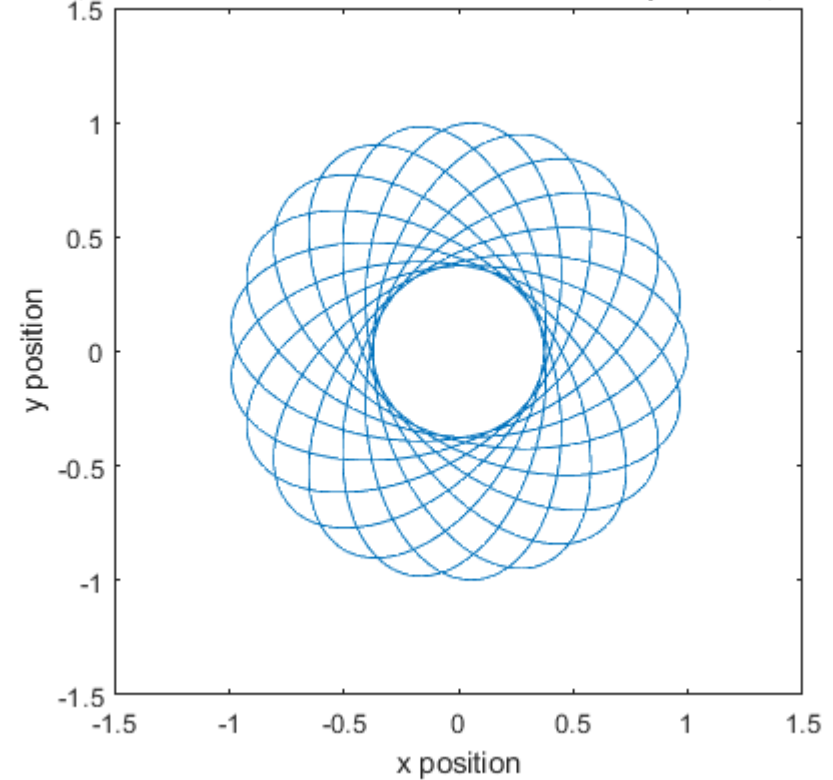


Central Force $F = -r^{-\frac{1}{2}}$

20 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 53.6122 s



21 Lobes, Constraint tolerance of 1e-05 with 1600 particles, T = 64.2172 s

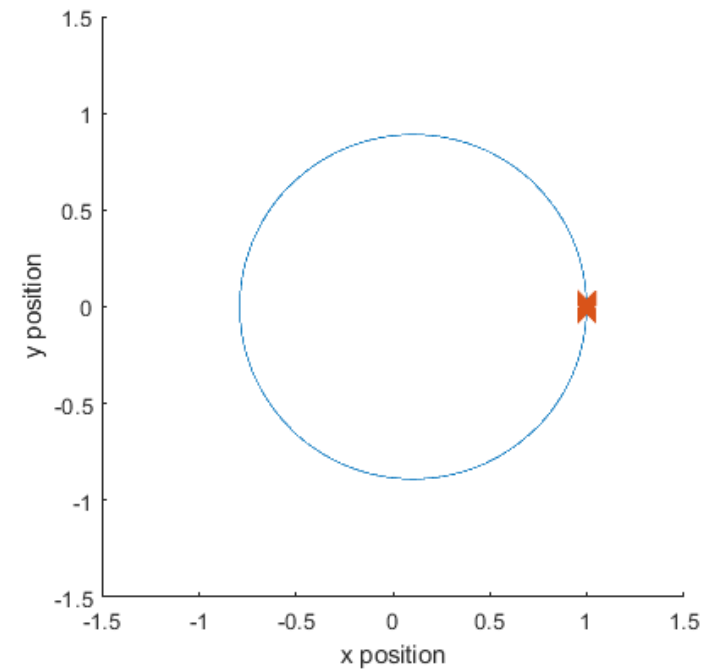
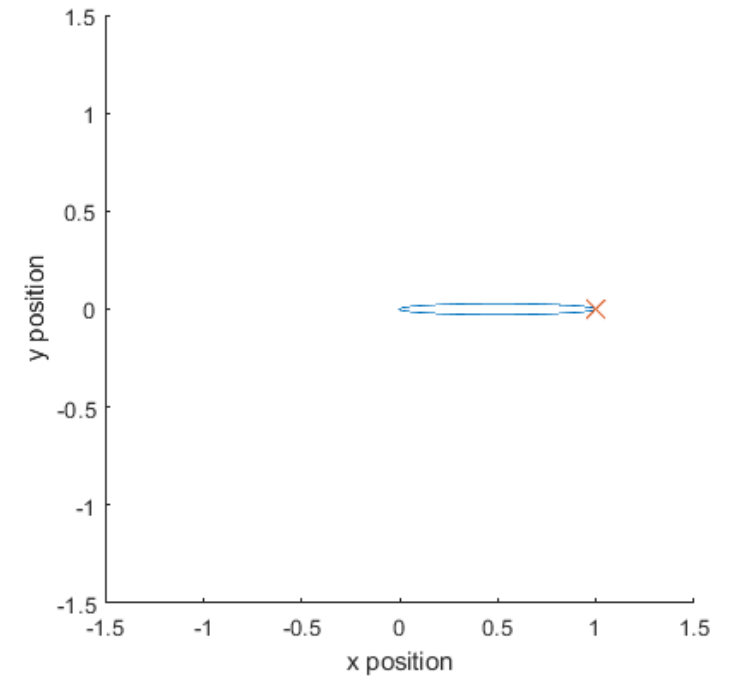


Single Shooting vs Multiple Shooting vs Collocation

- Attempt to converge to the same tolerance as that of ode45, so $1e-8$.
- Multiple shooting takes a very long time to converge. It will do it, but very slowly.
- Collocation sometimes works better than single shooting, sometimes not.
- Multiple shooting and collocation work better if the initial guess that is not as good.

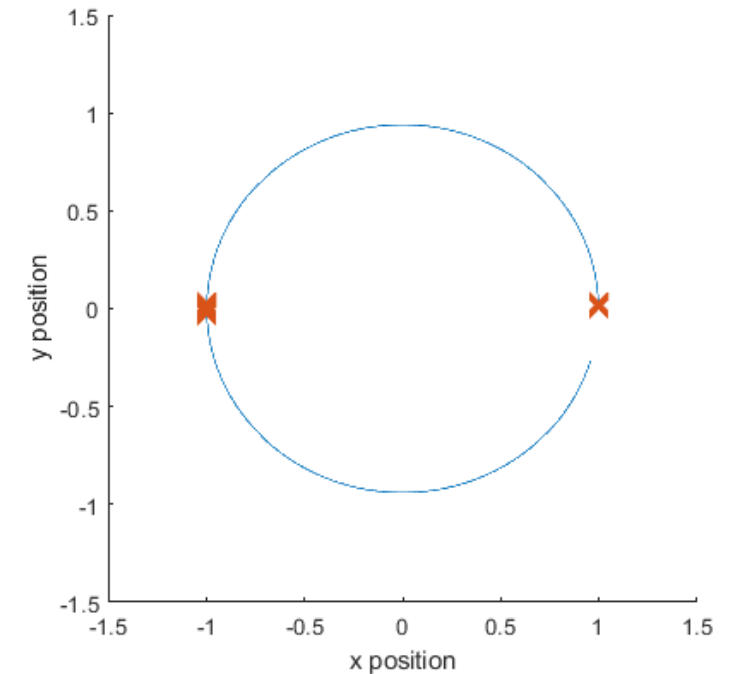
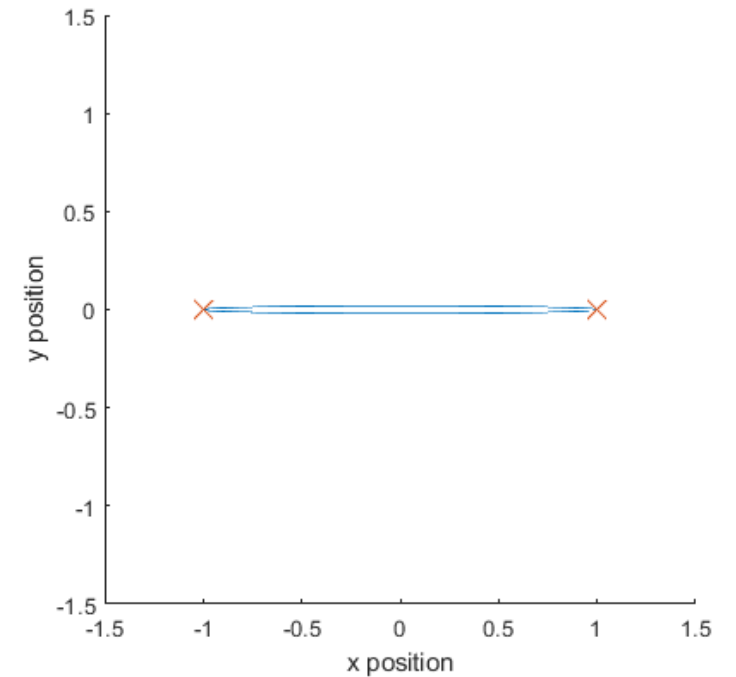
Other Central Forces

- $F = -r^{-2}$
- All trajectories are ellipses, or linear.
- The maximum must occur at the same point



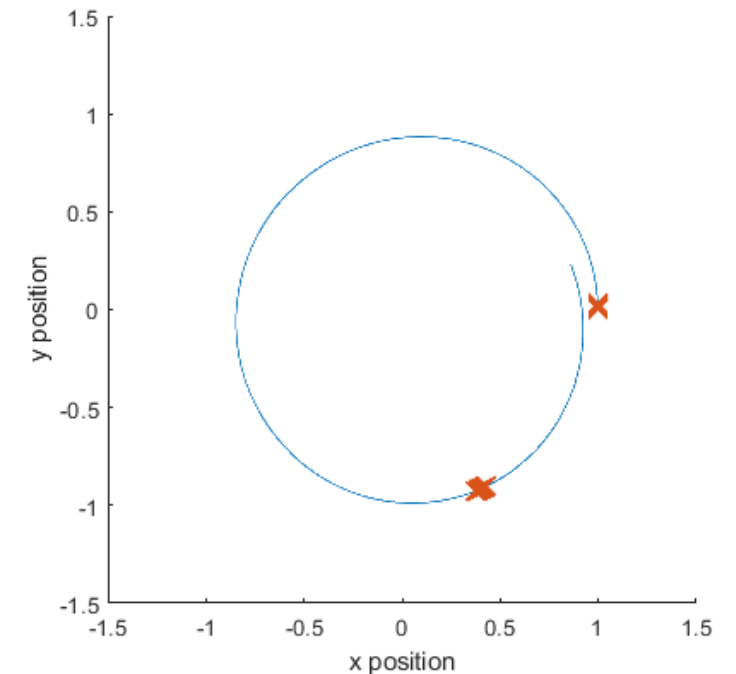
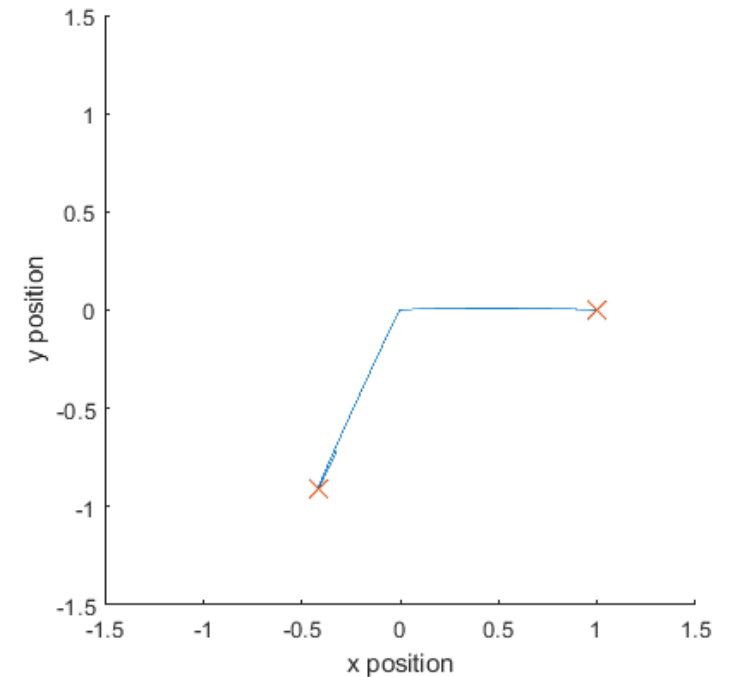
Other Central Forces

- $F = -r$
- All trajectories are ellipses, or linear.
- The maximum occurs 180° away.



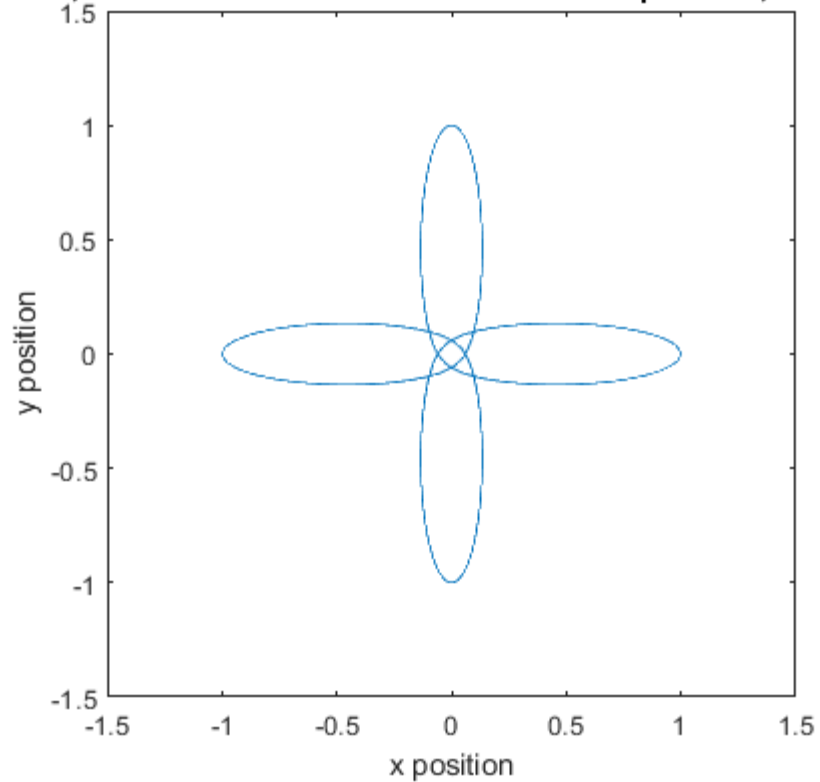
Other Central Forces

- $F = -r^{-\frac{3}{2}}$
- A different set of trajectories are possible/not possible.
- The location of the next lobe is bounded by $\sim(245^\circ, 343^\circ)$ away from the first lobe.

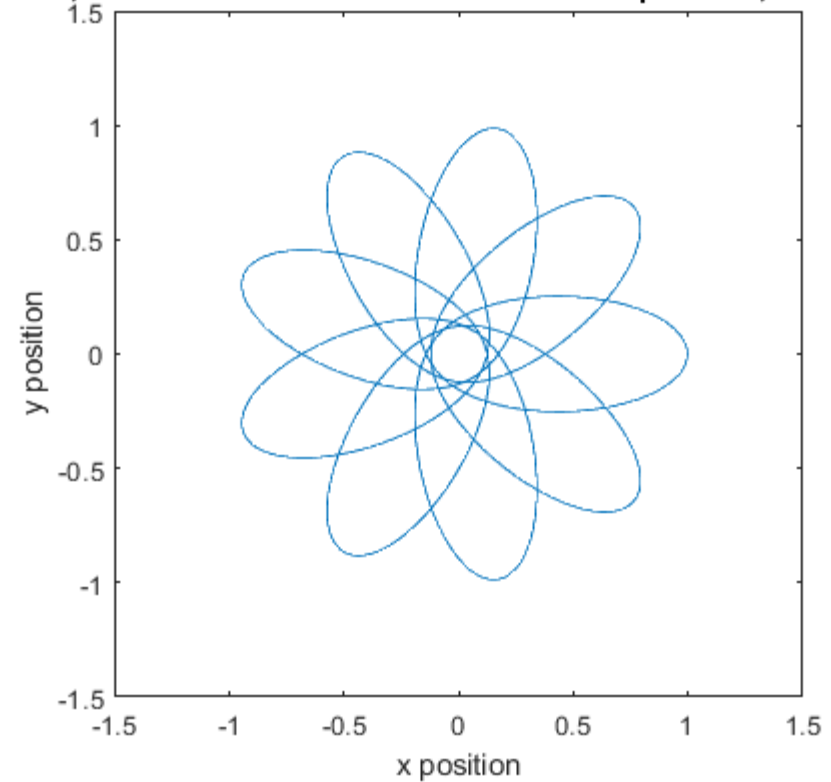


Central Force $F = -r^{-\frac{3}{2}}$

4 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 9.7257 s

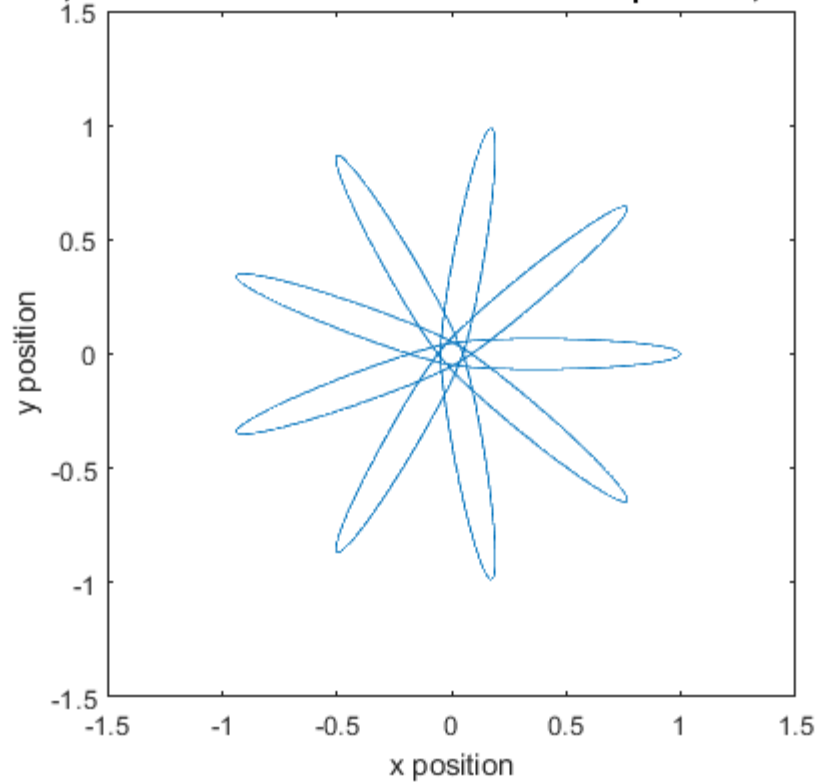


9 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 23.3174 s



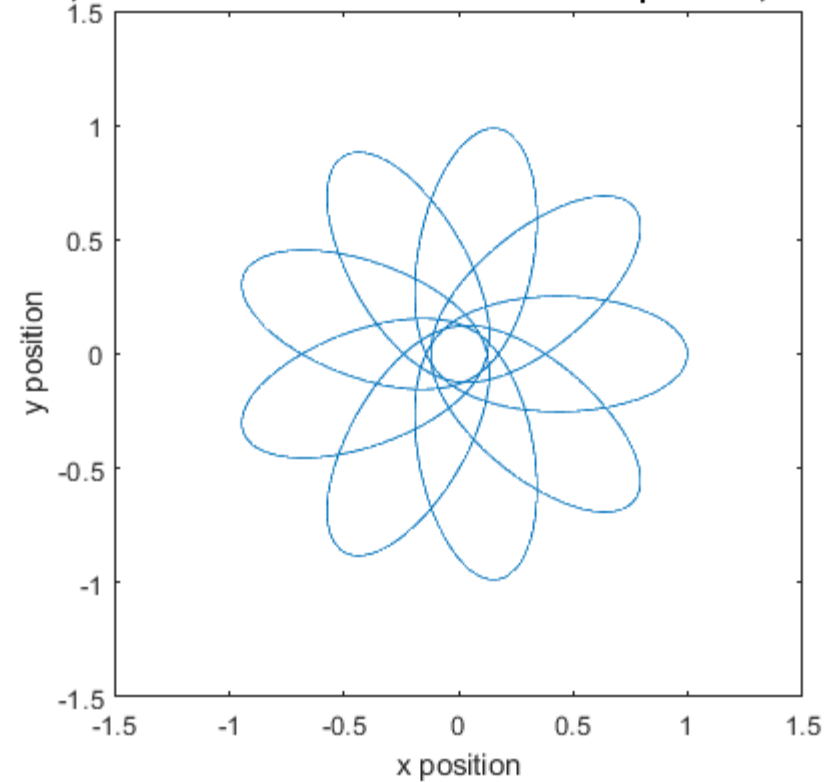
Central Force $F = -r^{-\frac{1}{2}}$

9 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 24.1761 s



Central Force $F = -r^{-\frac{3}{2}}$

9 Lobes, Constraint tolerance of 1e-06 with 1600 particles, T = 23.3174 s



Takeaways

- For $F = r^{-\frac{1}{2}}$, there does not exist a 3,4,6,10,14 lobed solution.
- For some lobed solutions, there exist multiple solutions, although their trajectory do not look identical.
- A particle subject to a central force is bounded by different angles. By looking at $[x \ y \ \dot{x} \ \dot{y}] = [1 \ 0 \ 0 \ 1]$, $v \in [0, 1]$, we can capture all the possible lobed solutions for a given central force.
- There appears to always be at least one solution after 14 lobes. (at least until 3000)
- The possible lobed solutions for each central force differs.
- Shooting is better when the guess is very close to the desired solution.
- To help convergence, it is sometimes useful to iterate, stepping up the tolerance.
- Impose constraints as tight as possible; double check that they are reasonable for the desired goal.